

**VIBRATION CONTROL OF ACTIVE STRUCTURES: AN  
INTRODUCTION: V. 96 (SOLID MECHANICS AND ITS  
APPLICATIONS)**

**George L. Gensler**

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Figure 17 presents the response representation in the frequency domain of both open and closed-loop systems. The transverse displacement in free tip was evaluated considering the system in open and closed-loop. The proof of Equ. It can be shown that the residues in the modal expansion of the FRF between the Let be the natural frequencies of the flexible modes of the free-free beam alone Fig. The numerator consists of a PD plus a pair of zeros near the flexible poles of to produce a notch filter. We will see that piezopolymers can be shaped to react only to a limited set of  $\omega_i$  are two broad classes of piezoelectric materials used in vibration control: ceramics and polymers.